

# Chapter 7

## Image Processing

### Edge Detection

Lecture *Digital Image Processing*, March. 12th, 2010

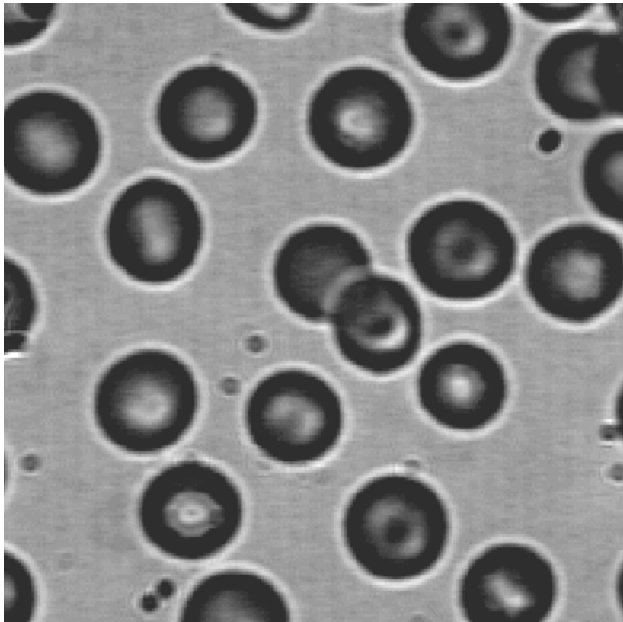


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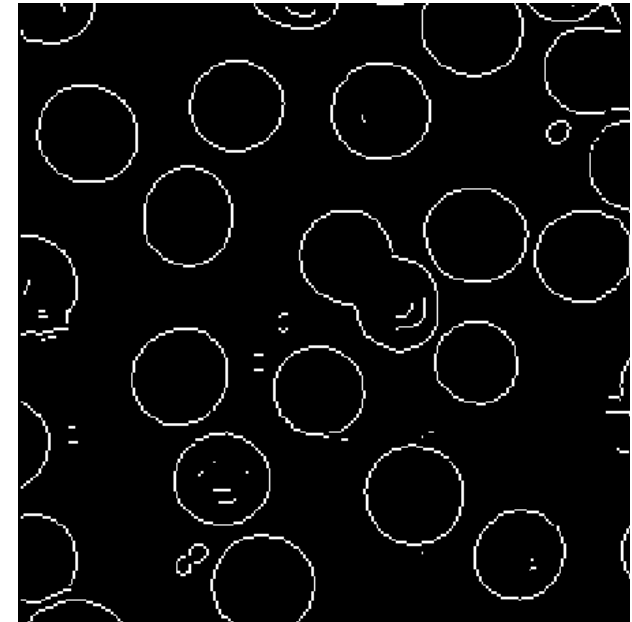


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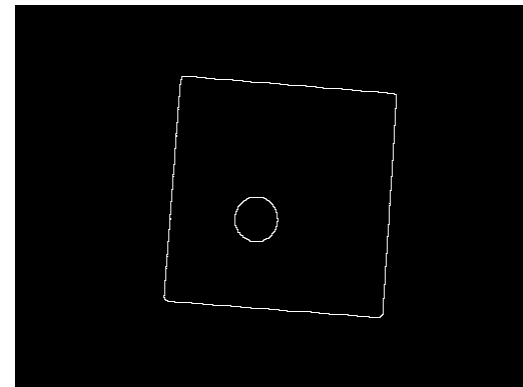
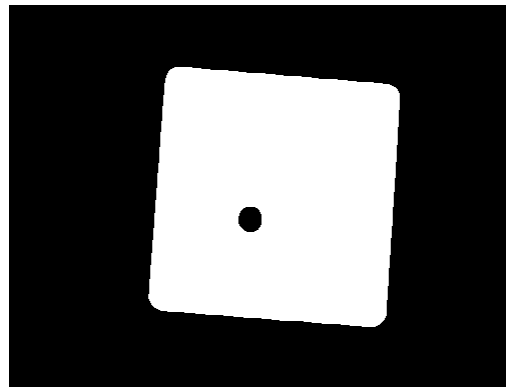
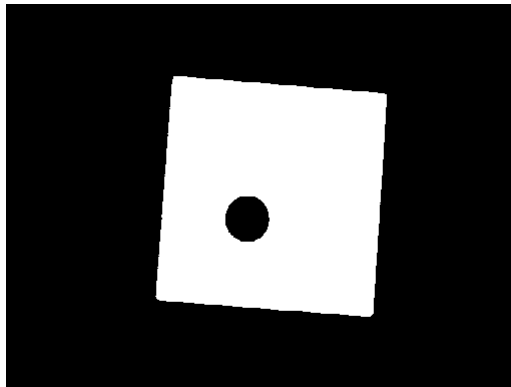
# What are edges?



Edge detection

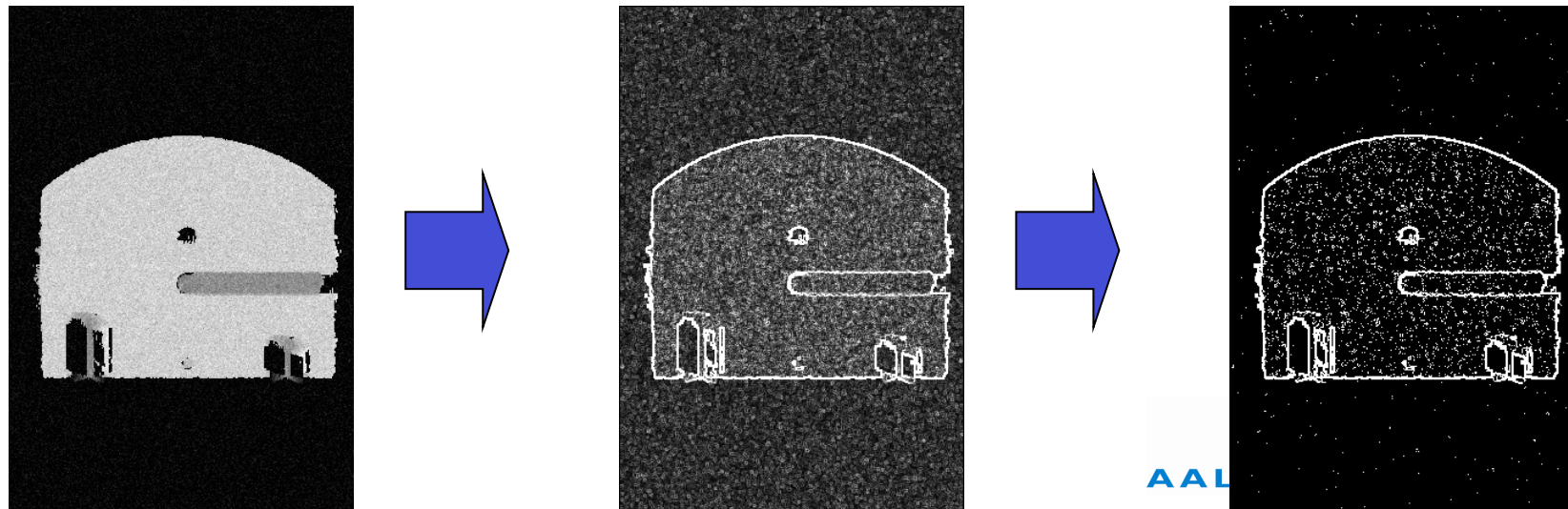
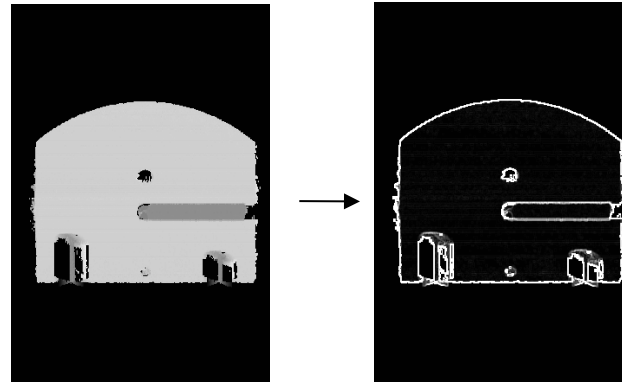


# How do we find them?

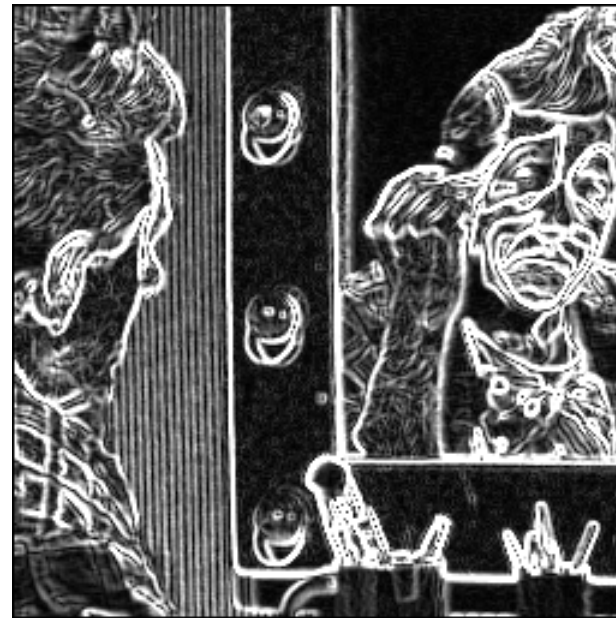
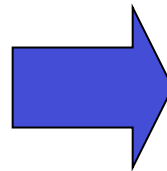


# Edges detectors

## The Noise Problem

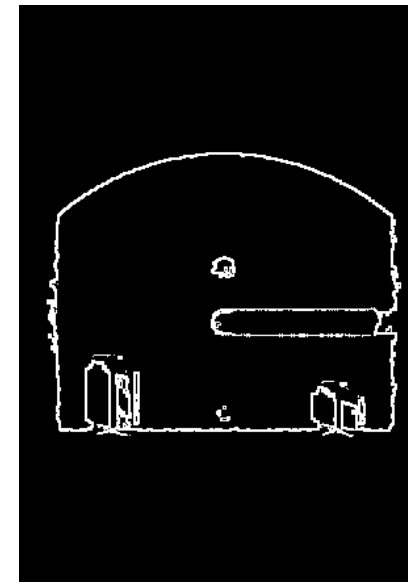
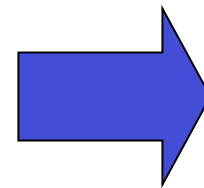
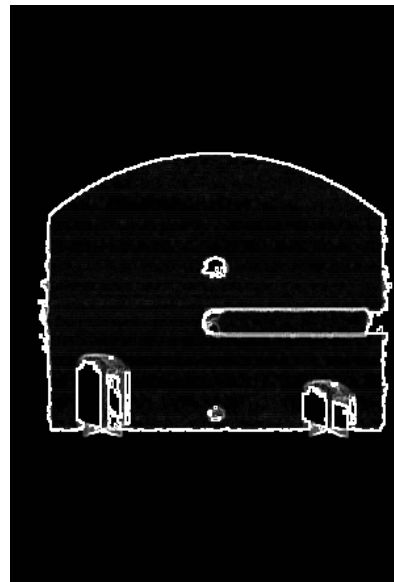
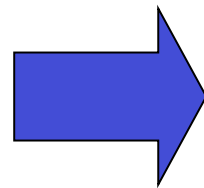


# Example for Sobel Operator



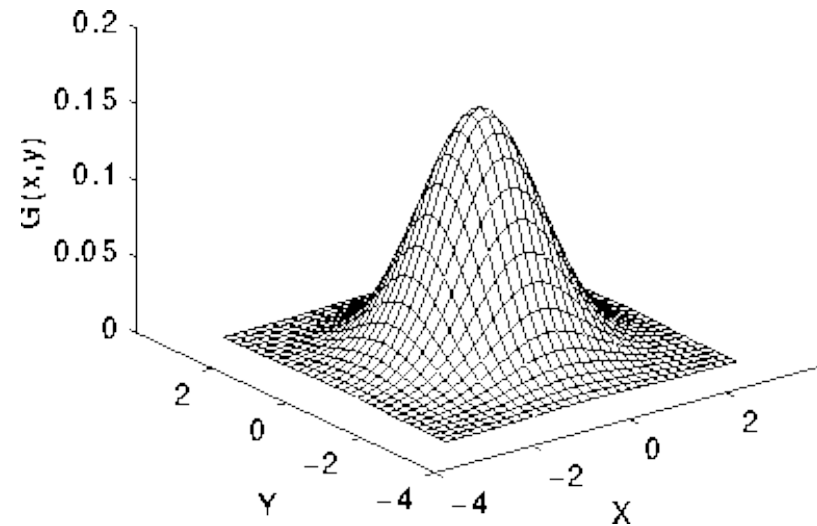
# Example for Sobel Operator

- Threshold: 150

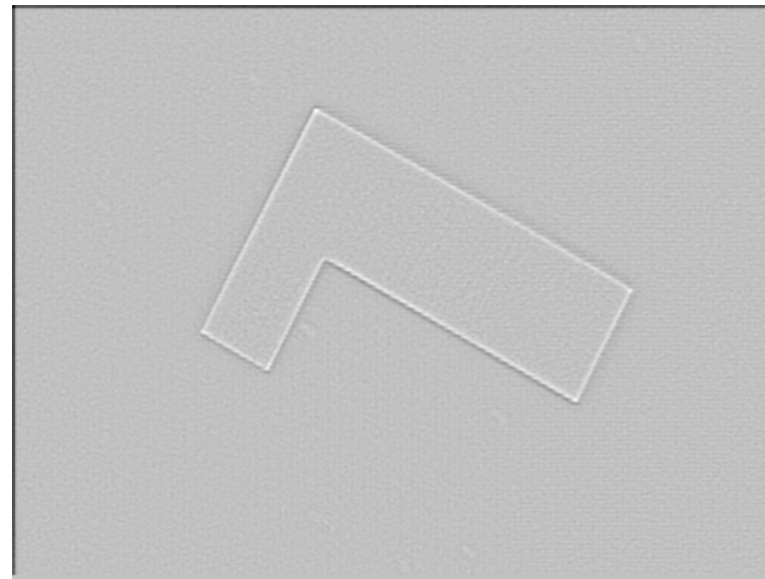
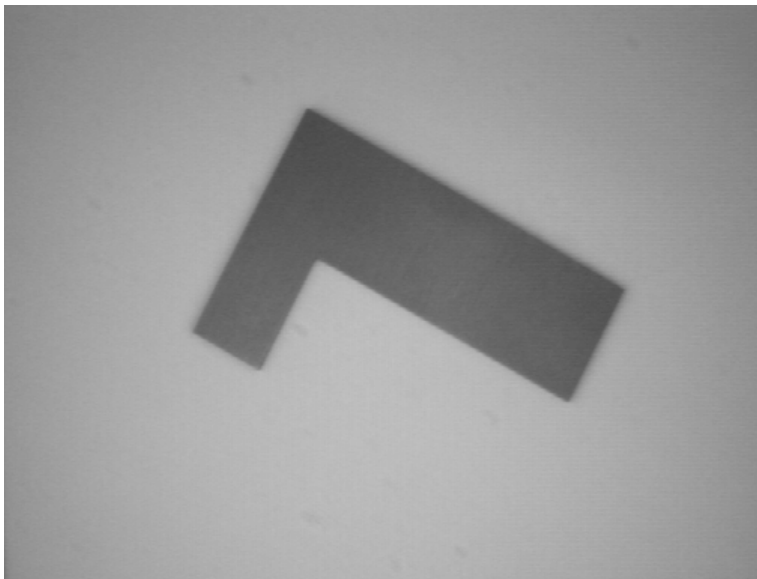


# Laplacian of Gaussian

- 2D Gaussian
- Used for smoothing



# Example for the LoG

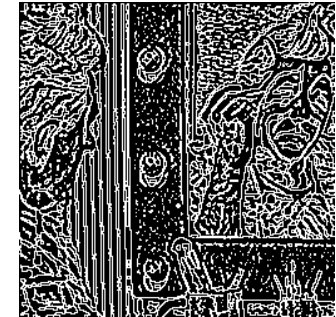




# Examples of LoG

Gauss filter width:

**5x5 pixels**



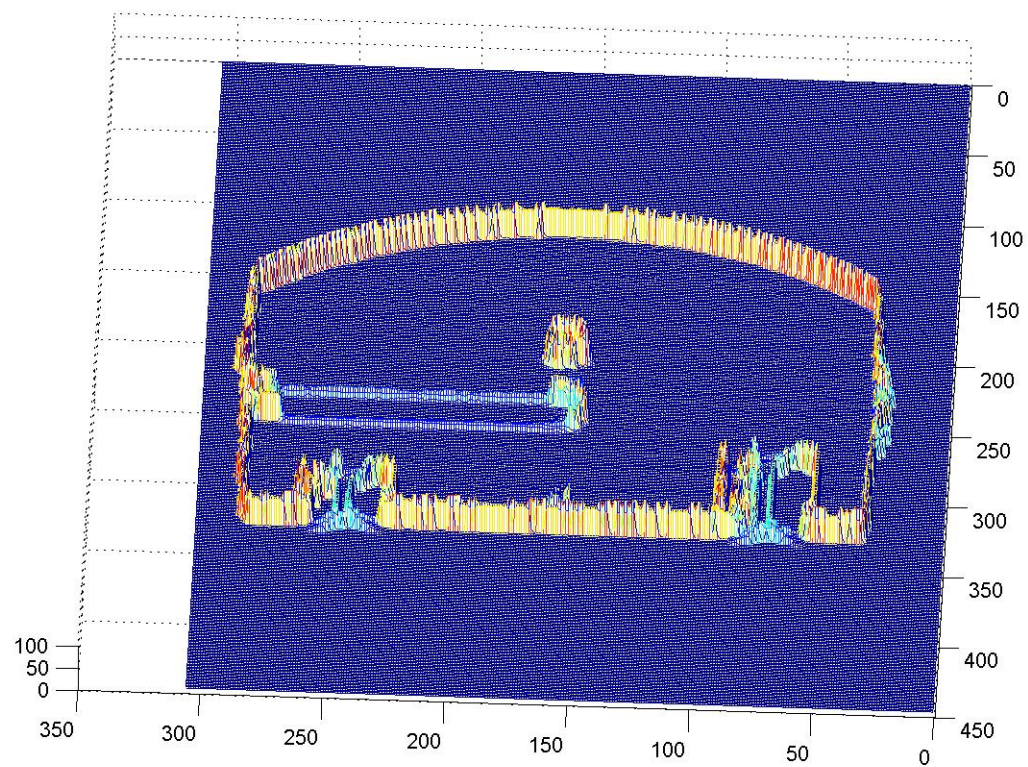
**9x9 pixels**



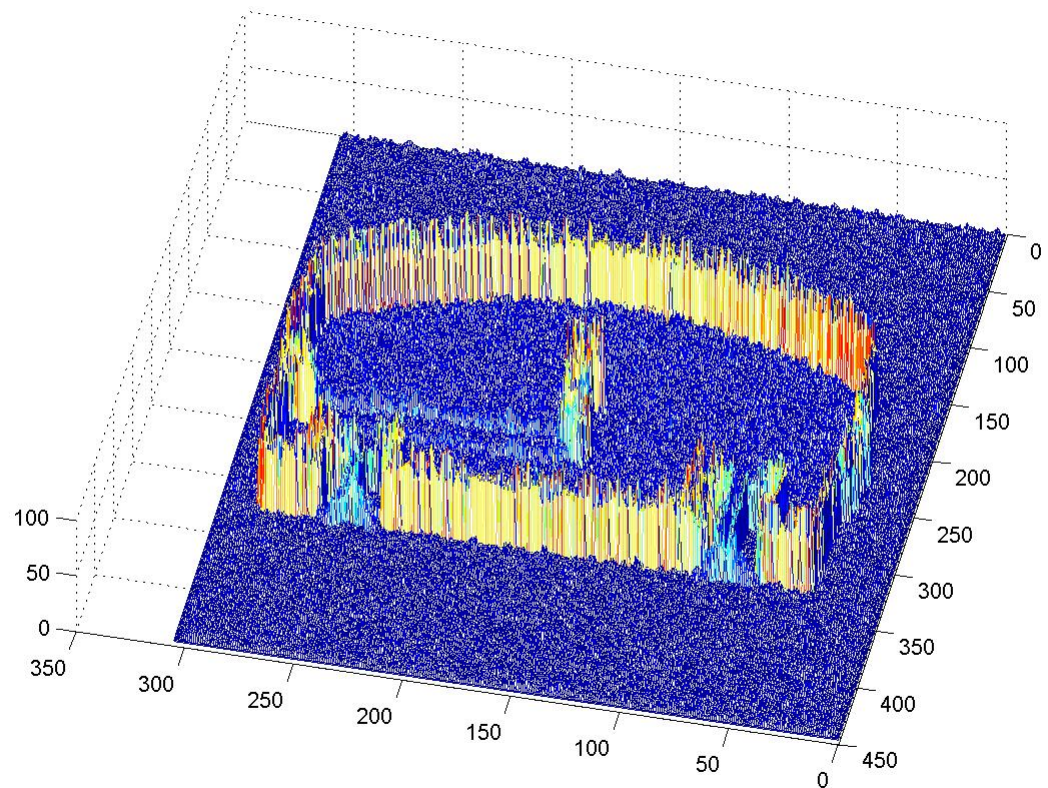
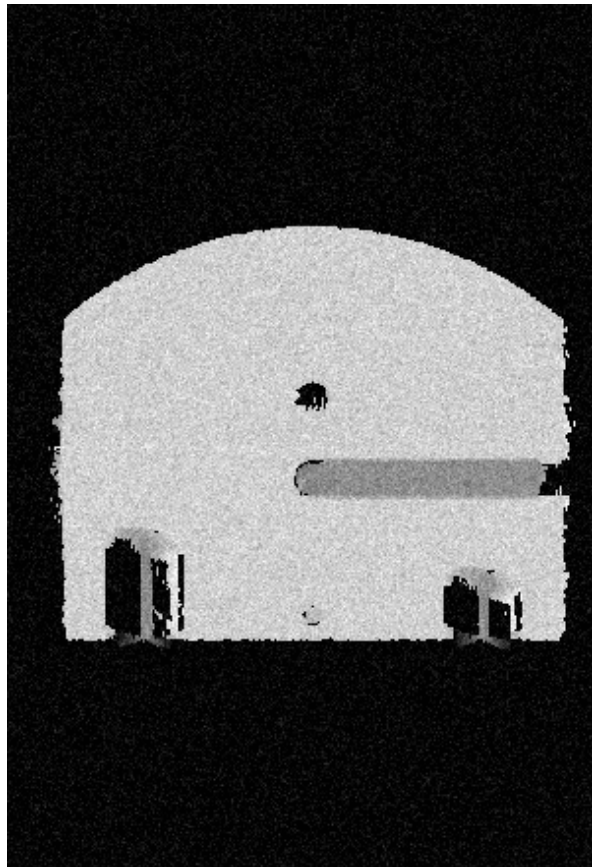
**12x12 pixels**  
9



# Example: 1<sup>st</sup> Derivative



# Example: 1<sup>st</sup> Derivative of Noisy Image



# Examples



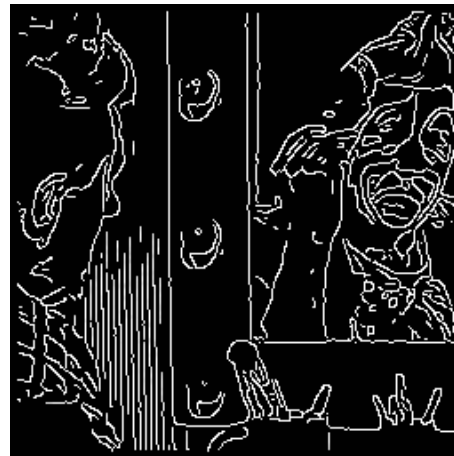
Gauss 5x5,  
 $Th_{\max} = 128$ ,  
 $Th_{\min} = 1$



Gauss 5x5,  
 $Th_{\max} = 255$ ,  
 $Th_{\min} = 1$



Gauss 5x5,  
 $Th_{\max} = 255$ ,  
 $Th_{\min} = 220$



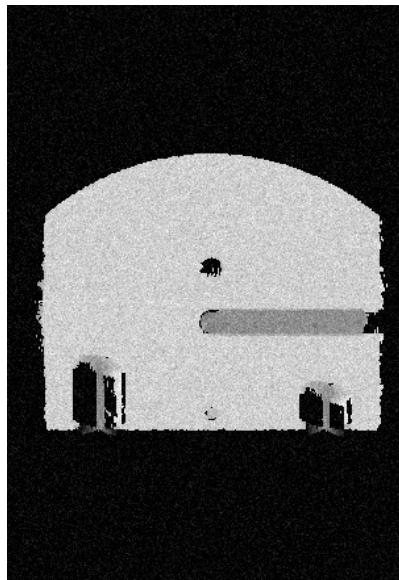
Gauss 9x9,  
 $Th_{\max} = 128$ ,  
 $Th_{\min} = 1$



# Examples

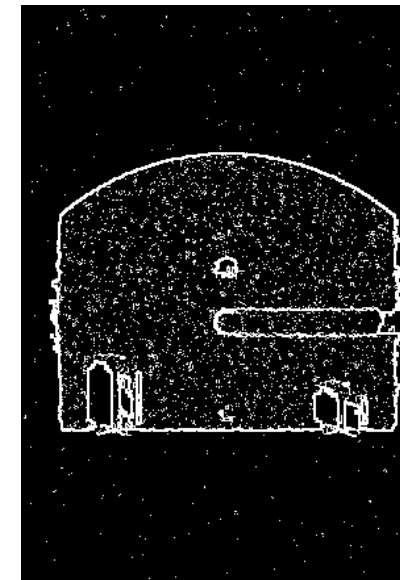
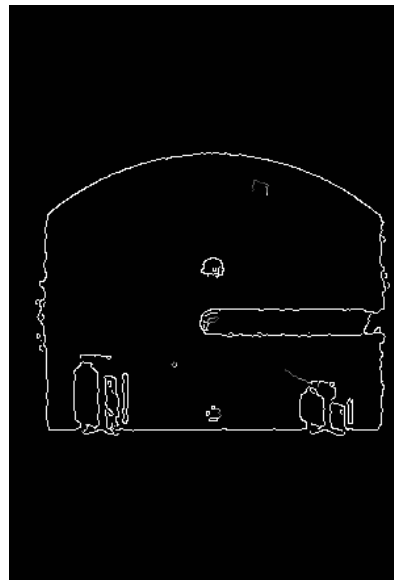
- Comparison on noisy image

Canny



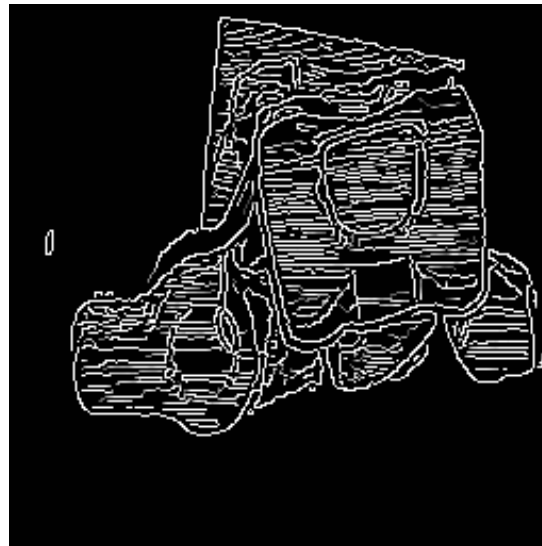
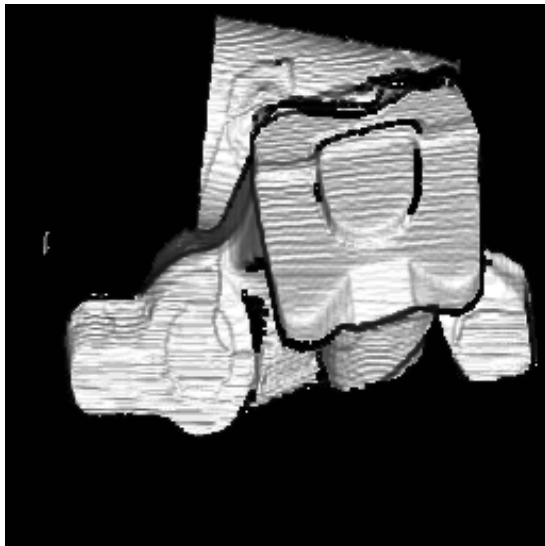
10

Sobel

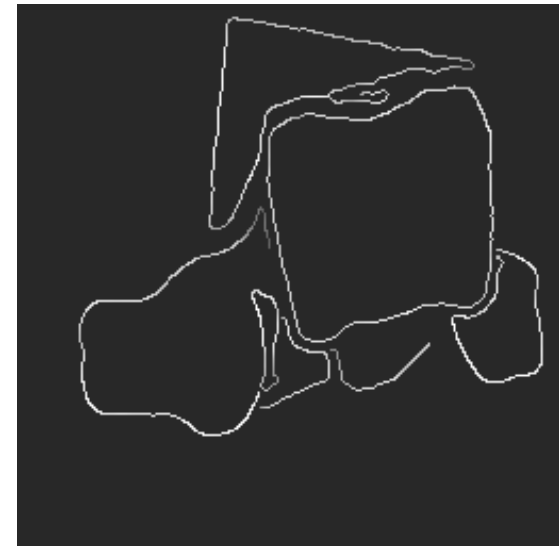


# Examples

Gauss 5x5,  
 $Th_{\max} = 200$ ,  
 $Th_{\min} = 1$



Gauss 7x7,  
 $Th_{\max} = 200$ ,  
 $Th_{\min} = 1$



# What to remember

- Edge = Rapid intensity (color) change
- Edge information is one of the most important in CV and Human Vision
- Three steps in edge detection:
  - Noise reduction
  - Edge enhancement
  - Edge localisation
- Three types were presented:
  - Based on first-order derivative
    - Prewitt and Sobel
  - Based on second-order derivative
    - Laplacian of Gaussian
  - Based on groups of edges
    - Canny

# Exercises

- Questions to the lecture?
- What was good about the lecture and what could have been better?
- Discuss the questions
- Discuss the principle of: non-maximal suppression
- Use C++/Matlab to generate a magnitude image using the Sobel kernels



# Questions

- Explain the relationship between image derivatives and edge detection
- What is the advantage of using the first/second derivative for edge detection?
- What filters are used to compute the first/second derivatives?
- what are the edge detection problems that are solved by the Canny edge detector?
- Explain in your own words how the Canny edge detector works.