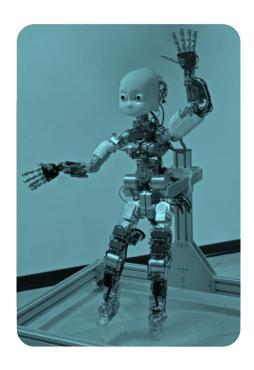


## The Mirror-Neurons System: data and models



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### Our approach

#### **Guiding Philosophy**

- Cognition cannot be hand-coded
- It is <u>necessarily</u> the product of a process of embodied development
- Initially dealing with immediate events
- Increasingly acquiring a predictive capability

COGNITION = PREDICTION



### Why?

 Purposeful manipulatory actions are founded on predictions of physical events and the effects of one's own actions





From Claes von Hofsten and Kerstin Rosander



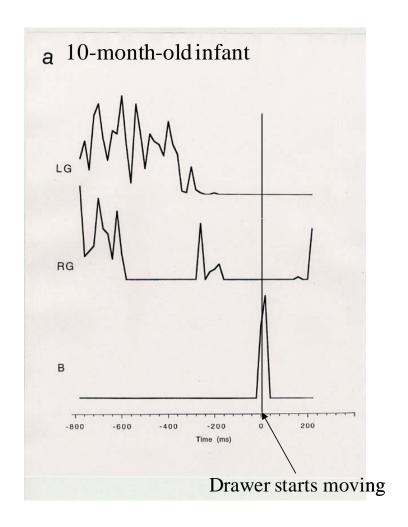
Infants in 10-17m range are very challanged when you put a toy in a drawer and close it. If they can, they will immediately open the drawer and take out the toy. Our drawer resisted opening by a weight attached to it.

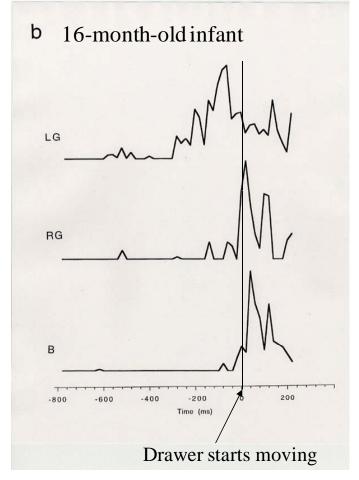


Pulling something that resists pulling has to start from the base of support. Adults will start the pull by activating the gastrocnemious muscles 50 ms before the arm starts pulling.

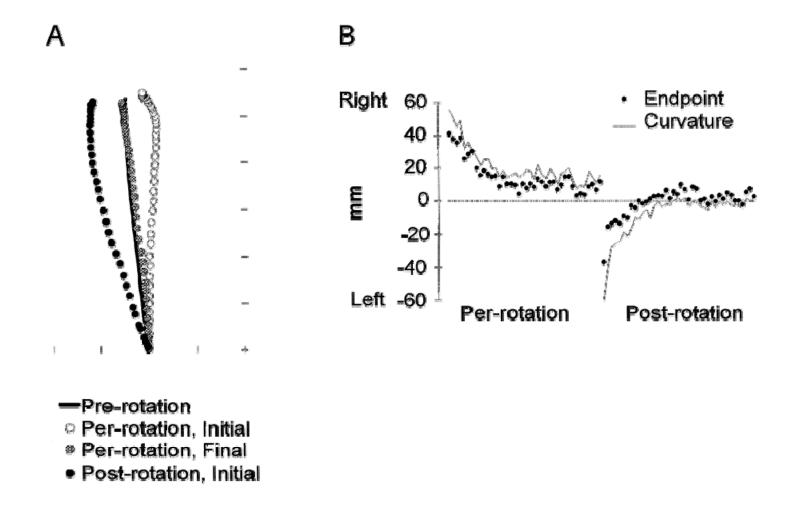
von Hofsten C., Rosander K., et al.





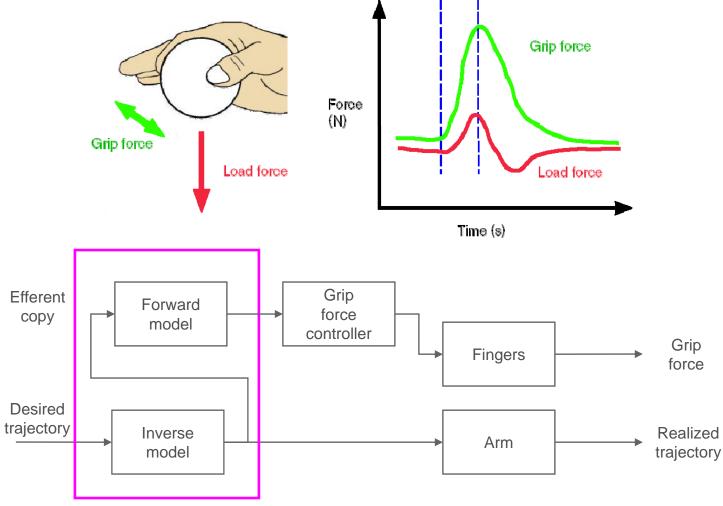






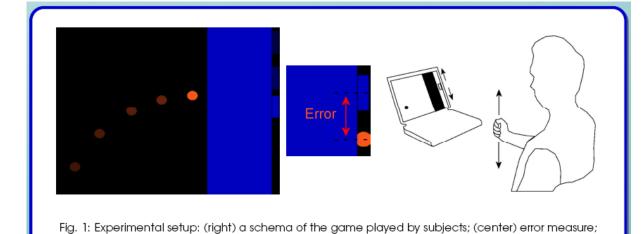
<u>From:</u> Lackner JR, Dizio P. *Gravitoinertial force background level affects adaptation to Coriolis force perturbations of reaching movements.* Journal of Neurophysiology 1998, 80:546-553.





<u>From:</u> Flanagan JR, Wing AM. *The role of internal models in motion planning and control: evidence from grip force adjustments during movements of hand-held loads.* Journal of Neuroscience 1997, 17:1519-1528.



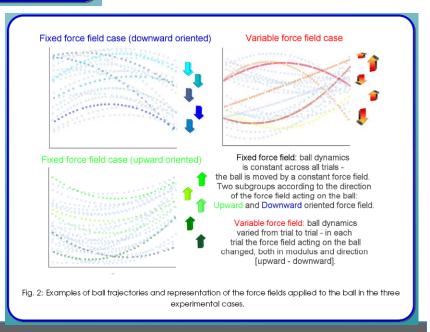


#### Experimental setup

(left) a sketch of an experiment. 28 subjects participated in the experiment.

Stimuli (3 conditions)

With Alessandra Sciutti, Francesco Nori, Thierry Pozzo





### Results

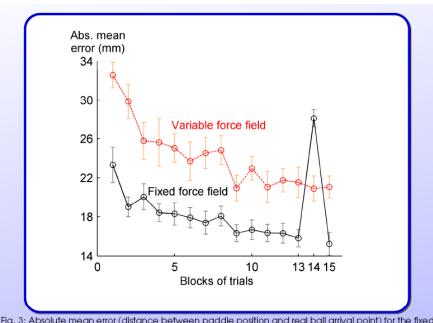


Fig. 3: Absolute mean error (distance between paddle position and real ball arrival point) for the fixed force field and the variable force field cases. Mean and standard error among subjects.

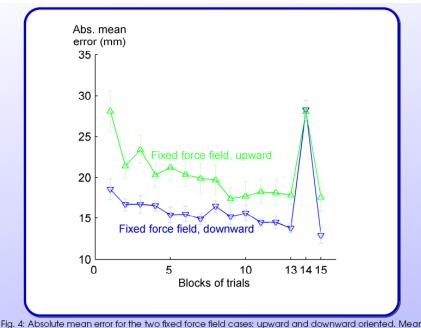
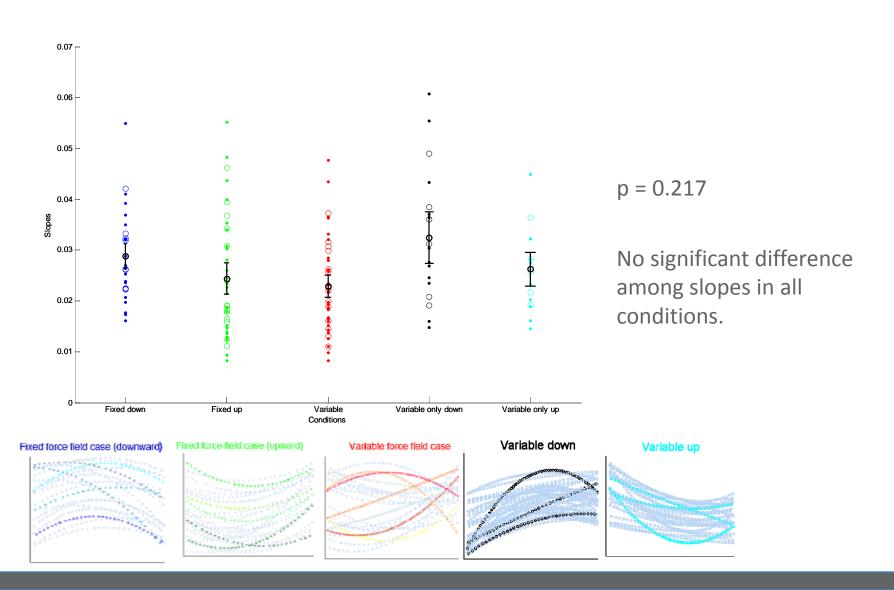


Fig. 4: Absolute mean error for the two fixed force field cases: upward and downward oriented. Mean and standard error among subjects.



### Results (vision only)

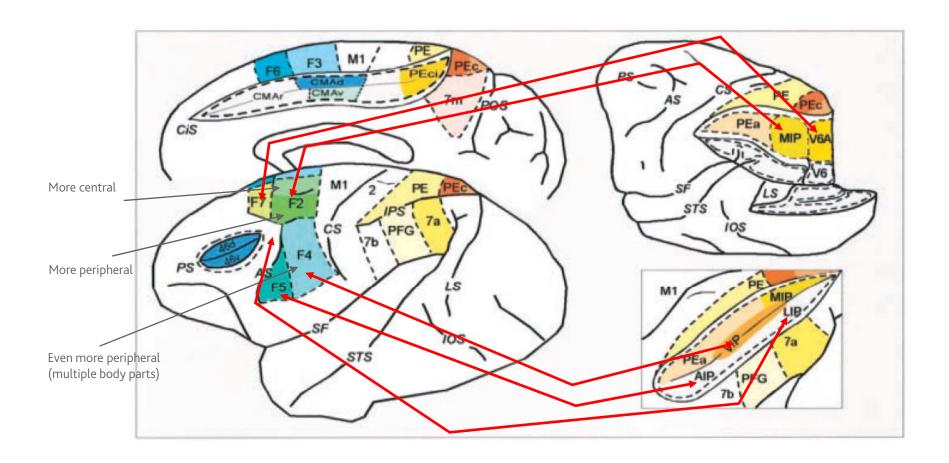




#### Conclusions

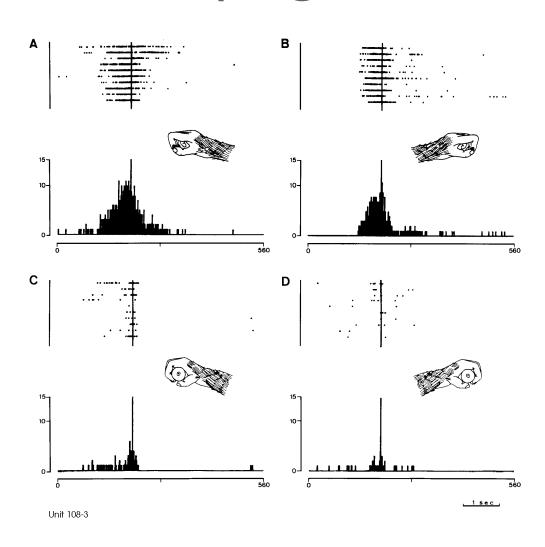
- In a predictive purely visual task, we **don't** find the same results as in the **motor** task.
- In a <u>purely visual task</u> prediction doesn't require the use of a <u>dynamical model</u>. In contrast to what happened in the motor task, performances aren't significantly better when a model of ball behavior can be built.
- Neither modulus nor orientation of the force field acting on the ball seems to have a predominant role in affecting predictive performances.







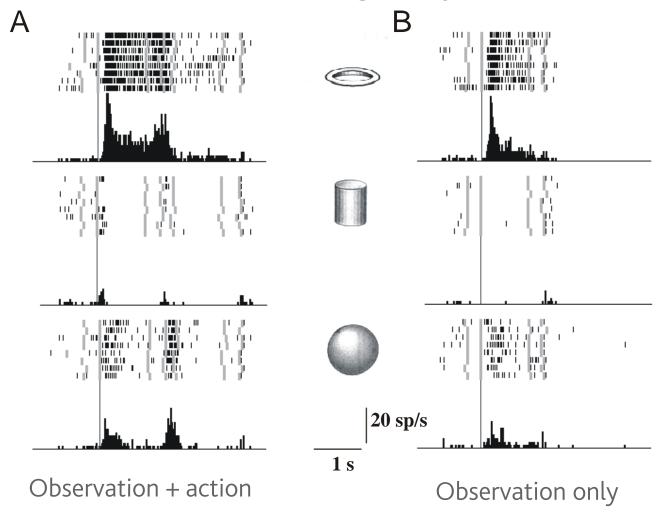
### Grasping neurons





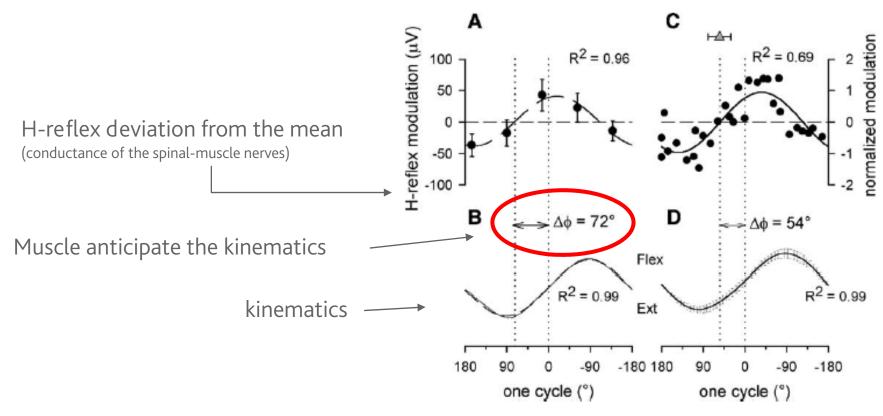
#### F5 canonical neurons

looking at objects





### Looking at others



Prone position, wrist ext/flexion (ECR, FCR muscles)

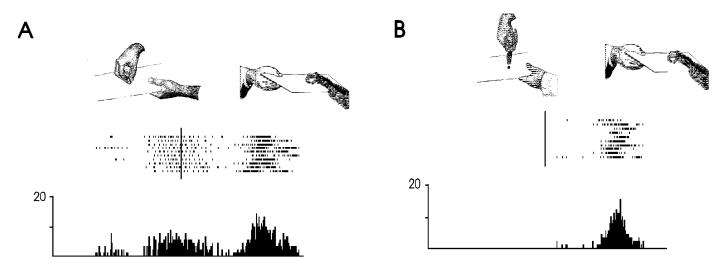
Borroni, P., Montagna, M., Cerri, G., & Baldissera, F. (2005). Cyclic time course of motor excitability modulation during the observation of a cyclic hand movement. *Brain Research*, 1065, 115-124.



#### Mirror Neurons

#### looking at others

The neuron is activated by "seeing" someone else's hand performing a manipulative action **and** while the monkey is performing the same action



The type of action seen is relevant

From: Fadiga, L., L. Fogassi, V. Gallese, and G. Rizzolatti, *Visuomotor Neurons: ambiguity of the discharge or "motor" Perception?* Internation Journal of Psychophysiology, 2000. **35**: p. 165-177.



### Speech listening...

European Journal of Neuroscience, Vol. 15, pp. 399-402, 2002

@ Federation of European Neuroscience Societies

#### SHORT COMMUNICATION Speech listening specifically modulates the excitability of tongue muscles: a TMS study

Luciano Fadiga, Laila Craighero, 1,2 Giovanni Buccino 2 and Giacomo Rizzolatti<sup>2</sup>

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Keywords: mirror neurons, mater-eyeked patentials, motor system, mater theory of speech perception



### The experiment

- Listening: three categories of stimuli (words, pseudowords, bi-tonal sounds).
- Two phonemes 'rr' requires strong tongue tip movement, 'ff' requires slight tongue tip movement.
- TMS of the under-threshold motor cortex.
- Recording of the MEP (motor-evoked potential) from the tongue muscles.

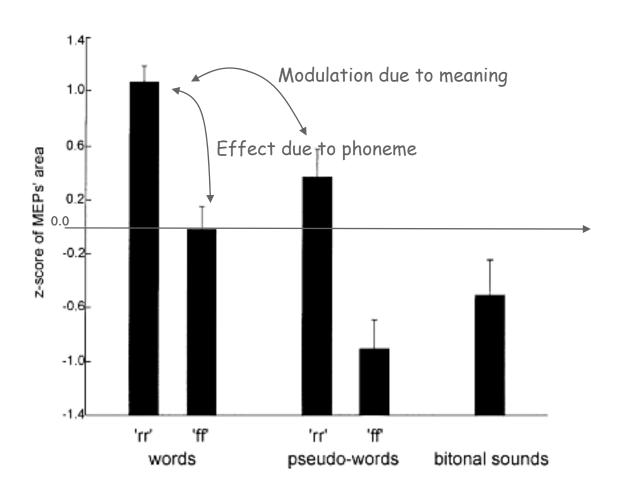


# Examples of word/pseudo-words

Labiodental fricative consonant, 'rr'		Lingua-palatal fricative consonant, 'ff'	
Words	Pseudo-words	Words	Pseudo-words
birra (bier)	berro	baffo (moustache)	biffo
carro (cart)	firra	beffa (hoax)	ciffo
cirro (cirrus)	forro	buffo (funny)	<b>l</b> effa
farro (spelt)	furra	ceffo (snout)	meffa
ferro (iron)	marro	coffa (crow's nest)	paffo
mirra (myrrh)	merro	goffo (clumsy)	peffa
morra (morra)	parro	muffa (mold)	poffa
porro (leek)	perro	puffo (smurf)	seffa
serra (greenhouse)	vorro	tuffo (dive)	viffa
terra (ground)	vuito	zaffo (plug)	voffo

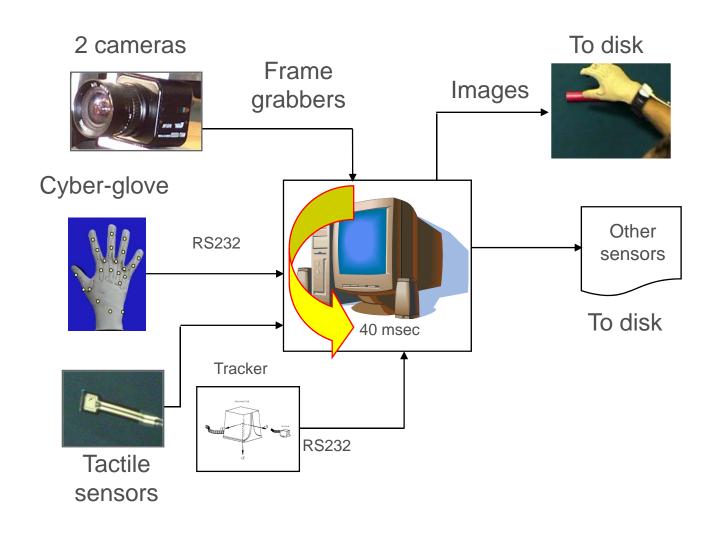


### Results (in short)





### Data from human grasping





### Bayesian classifier

{*Gi*}: set of gestures **F**: observed features {*Ok*}: set of objects

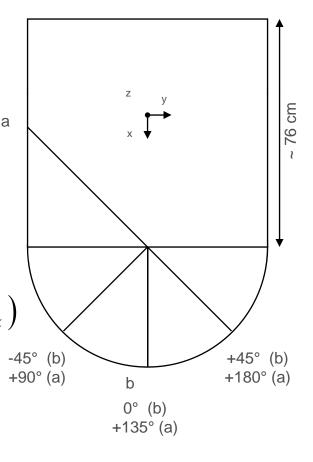


p(Gi|Ok): priors (affordances) p(F|Gi,Ok): likelihood to observe **F** 

$$p(G_{i} | \mathbf{F}, O_{k}) = p(\mathbf{F} | G_{i}, O_{k}) p(G_{i} | O_{k}) / p(\mathbf{F} | O_{k})$$

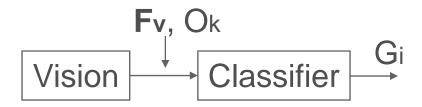
$$\hat{G}_{MAP} = \arg \max_{G_{i}} (G_{i} | \mathbf{F}, O_{k})$$

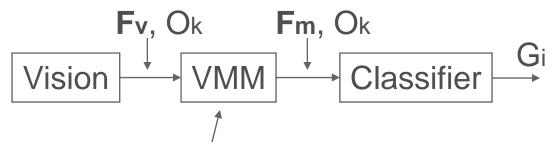
168 sequences per subject
10 subjects
6 complete sets





### Two types of experiments





Learned by backpropagation ANN



# Role of motor information in action understanding

