

Yet Another Robot Platform

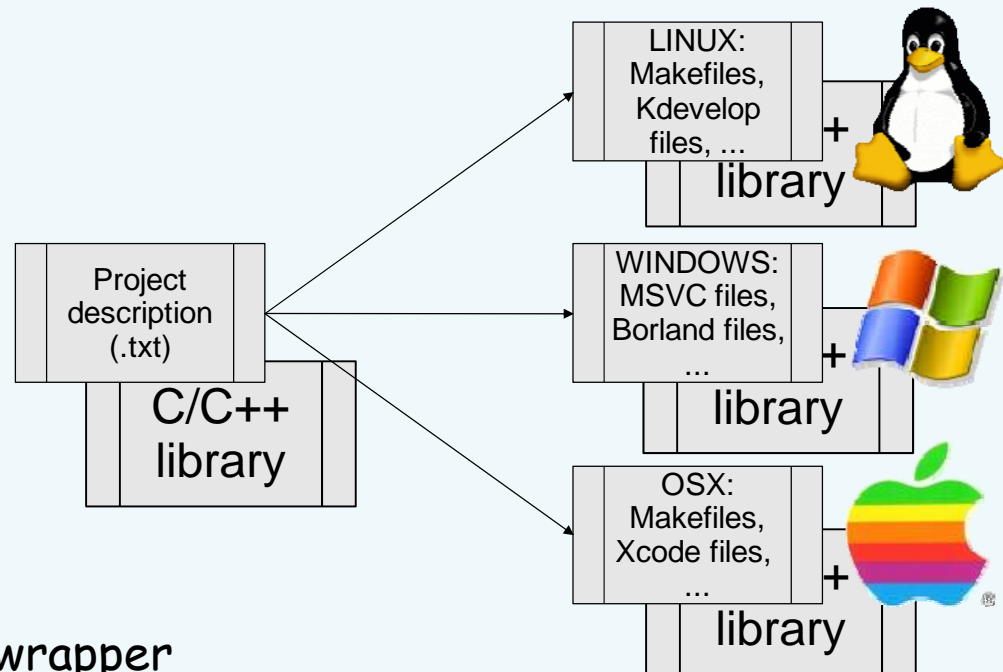
- YARP is an open-source middleware for humanoid robotics
- History
 - An MIT / Univ. of Genoa collaboration
 - Born on Kismet, grew on COG
 - With a major overhaul, now used by RobotCub consortium
 - Exists as an independent open source project
 - C++ source code



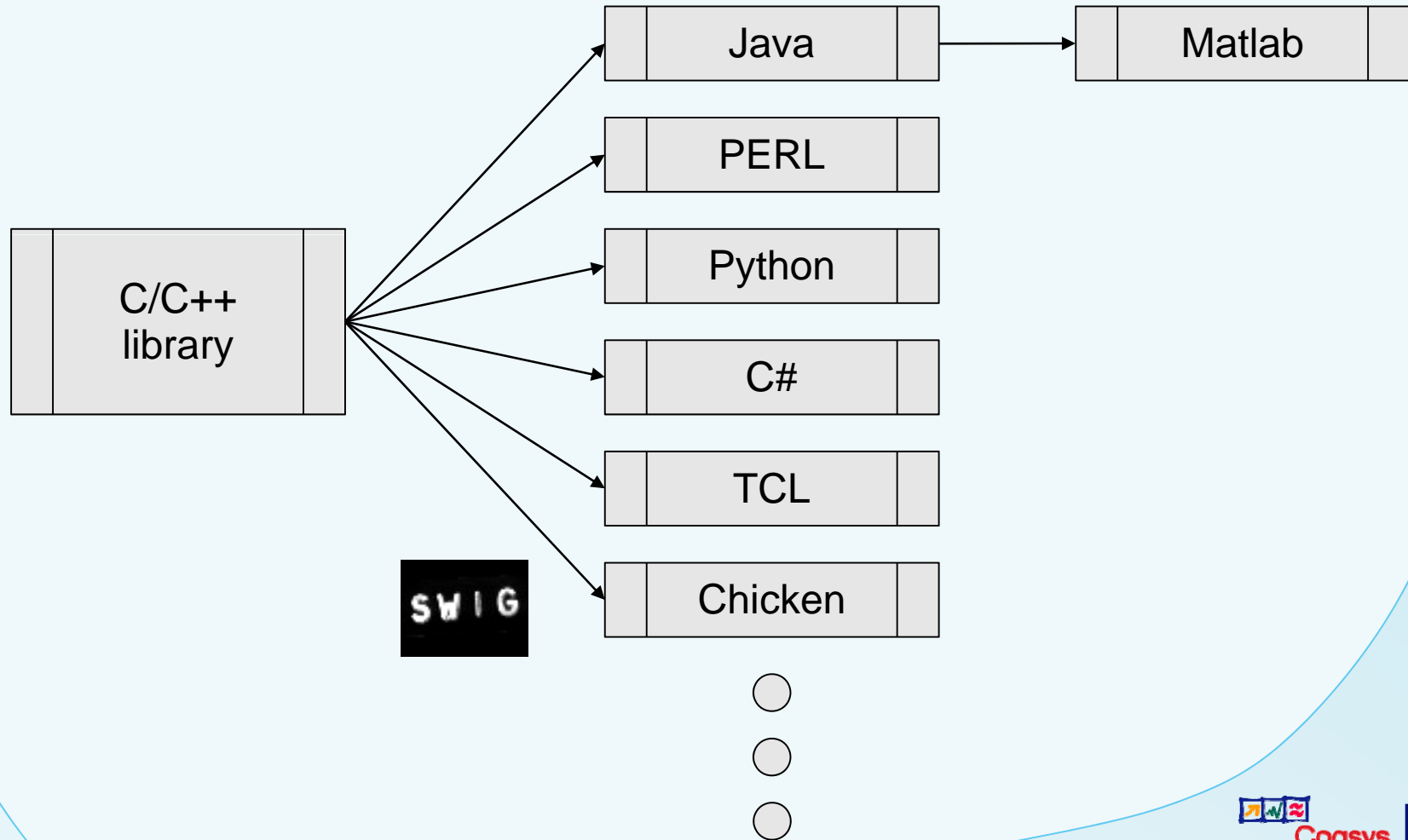
IDE/OS Portability



OS portability
C++ OS functionality wrapper
e.g. threads, semaphores, sockets



Language Portability (SWIG)



What is YARP for?

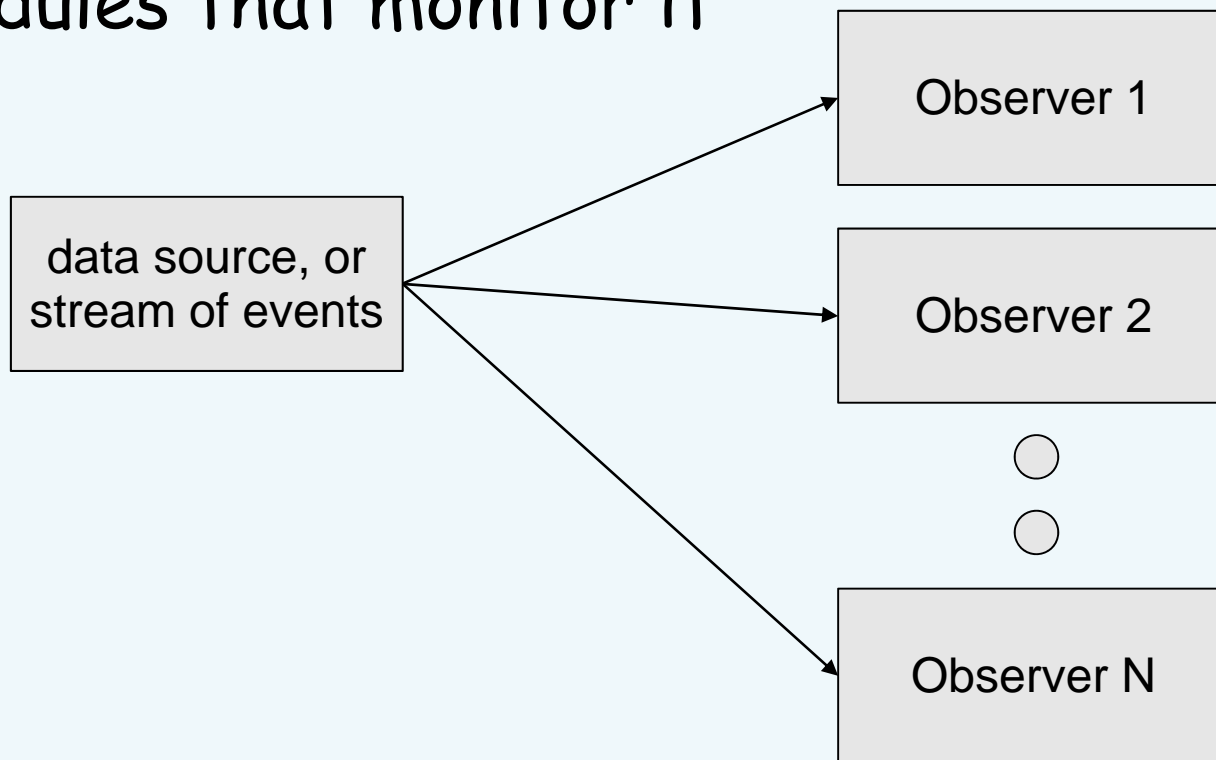
- Factor out **details of data flow between programs** from program source code
 - Data flow is very specific to robot platform, experimental setup, network layout, communication protocol, etc.
 - Useful to keep “algorithm” and “plumbing” separate
- Factor out **details of devices used by programs** from program source code
 - The devices can then be replaced over time by comparable alternatives; code can be used in other systems

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the Observer pattern

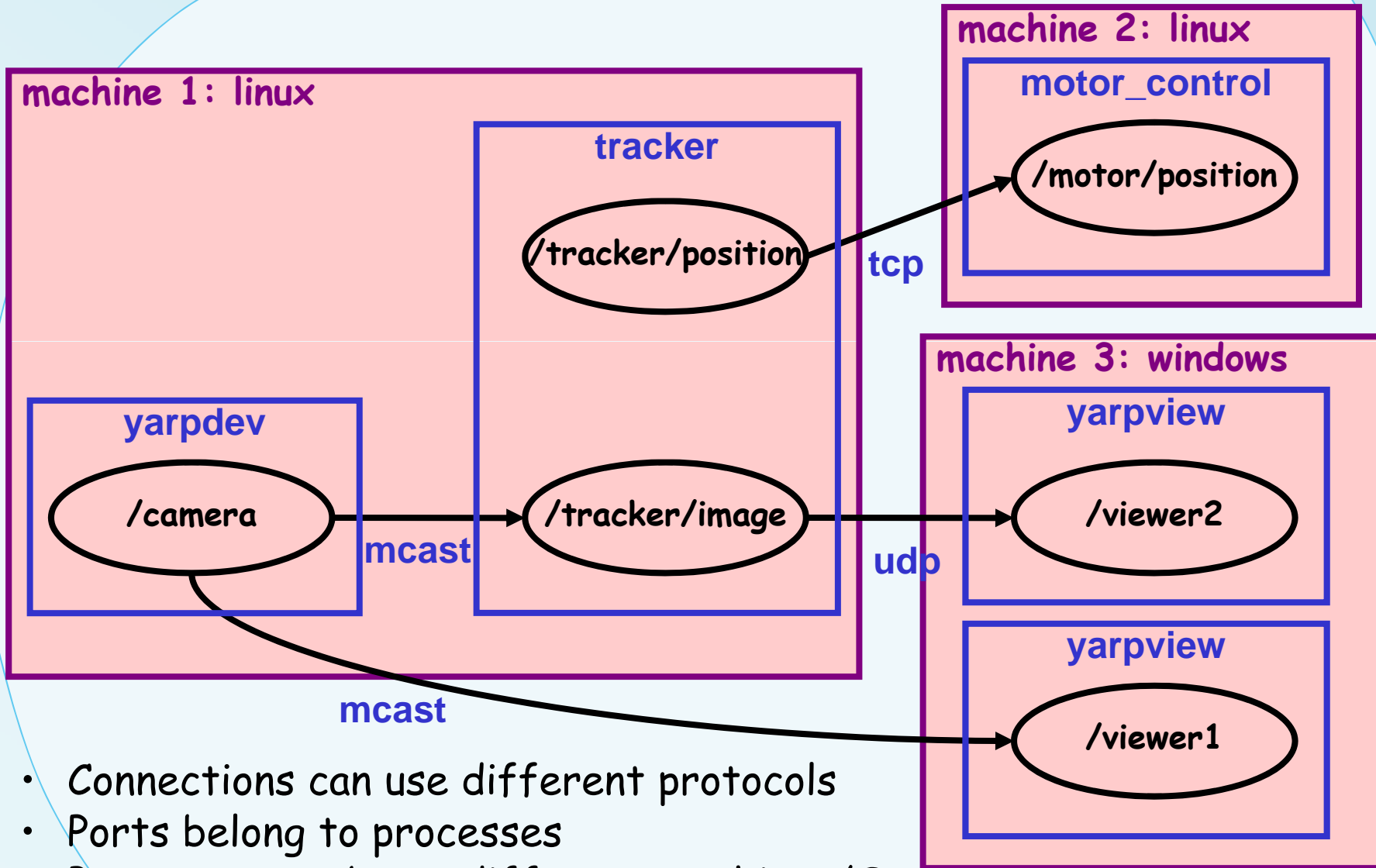
- Data source knows nothing about identity of modules that monitor it



YARP Ports

- We follow the **Observer** design pattern.
- Special "Port" objects deliver data to:
 - Any number of observers (other "Port"s) ...
 - ... in any number of processes ...
 - ... distributed across any number of computers/OSes ...
 - using any of several underlying communication protocols with different technical advantages, streaming or RPC
- This is called the YARP Network

Typical YARP Network

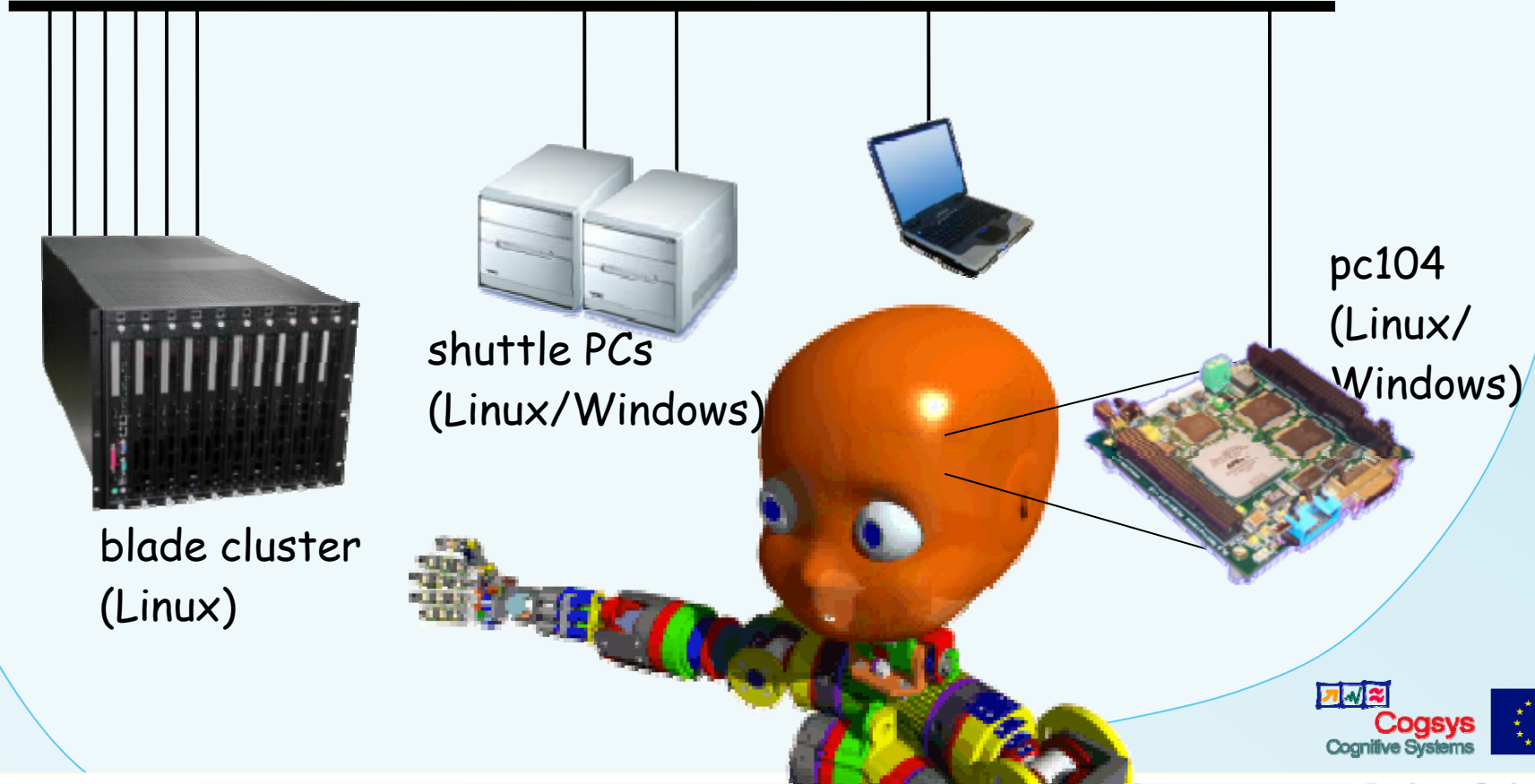


- Connections can use different protocols
- Ports belong to processes
- Processes can be on different machines/OS

Physical Network

Example: RobotCub

Gigabit Ethernet (with tcp, udp, multicast traffic)



Why is all this useful?

- We've separated out most of the **plumbing**
- We get to change it **dynamically** (handy)
- More importantly, we have better **modularity**
 - Programs can be **moved around** as load and OS/device/library dependencies dictate
 - Fundamental protocol for communication can be **changed** without affecting programs
 - Better chance that your code can be **used by others** (even just within your group)